



EIGER integration in MXCuBE

Mikel Eguraun - mikel.eguraun@maxiv.lu.se

Jie Nan- jie.nan@maxiv.lu.se

Outline

- Eiger communication recap
- EIGER Tango device and MAXIV additions
- Additional remarks



Eiger Control interface

- EIGER Firmware version 1.6.4
- SIMPLON API version 1.6.0
- Web interface for simple operations and testing
 - initialize, upgrade, testing, network, logging
- REST API
 - complex configuration
 - experiment control
- zeromq streaming

DECTRIS
detecting the future

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EIGER API Log
System Settings

Eiger Detector System

EIGER Status

EIGER Firmware version	1.6.4
SIMPLON API version	1.6.0
Control Unit S/N	123456
Detector S/N	E-00-0000
Network 10 GBit/s (em1)	172.16.115.4
Network 10 GBit/s (em2)	172.16.115.5
Network 1 GBit/s (em3)	172.16.118.44
Network 1 GBit/s (em4)	10.42.42.20

For more information contact our [support team](#)

Simplon API

- HTTP GET, PUT operations

- Resources are identified as (e.g.):

“`http://<IP_of_DCU>/<module>/api/<api version>/task/<parameter>`”

- where:

- module: detector, monitor, file writer, stream, system

- task: config, status, command

- each module has different parameters

- GET at `http://172.16.118.44/detector/api/1.6.0/config/photon_energy`

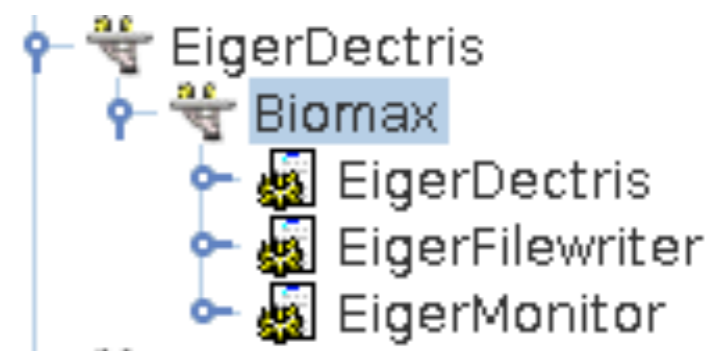
- Documented API

```
{  
  "min": "5000.0",  
  "max": "36000.0",  
  "value": "12660.0",  
  "value_type": "float",  
  "access_mode": "rw",  
  "unit": "eV"  
}
```

Eiger tango device

- Independent of MXCuBE: very useful for testing
- Thanks to T. Nuñez (DESY)
- Multiclass device: a tango device per ~module
- python
 - *request* library for HTTP GET PUT
 - easy to add attributes

```
response = requests.get(url, timeout=timeout)
data = json.loads(response.text)
return data["value"]
```



<http://svn.code.sf.net/p/tango-ds/code/DeviceClasses/Acquisition/2D/EigerDectris/>

<https://github.com/MaxIV-KitsControls/dev-maxiv-eigerdectris>

Eiger tango device

- MAXIV additions:
 - Some new attributes
 - fixes for latest simplon api bugs and operation
 - *Might* not work properly with versions < 1.6
 - spawn/stop dcu data backup procedure
 - cleanup and status/state management
 - check for path collision before arm/trigger
 - increasing timeout
 - status update after cancel/abort
 - increased timeout in some attr
 - update x,y pixel size when roi changes
 - Implement DcuBufferFree attribute
 - Remove mask attributes
 - Fix status_update and wait commands
 - Prepare trigger detection in Arm command
 - Add wait_for_trigger command in the detector
 - Send status_update before requesting temperature/humidity
 - Send status_update command before requesting state
 - pixel size x,y; pixels in detector x,y
 - do no reset flag_arm right after arming (ready status)
 - roi mode argument values, 4M and disabled
 - When reading Frametime update min/max values as well
 - removing pixel mask, big array causing problems
 - Roi mode attribute, check supported values!
 - added compression attribute, supported values: lz4, bslz4
 - Pixel mask stuff
 - Omega stuff
 - detector distance attribute
 - added beam center x,y configuration attributes

Eiger tango device

EigerDectris class

- Attributes:

'NbTriggersMin', 'Temperature', 'Time', 'FrameTime', 'NbTriggersMax', 'YPixelSize', 'Compression', 'OmegaIncrement', 'DownloadDirectory', 'TriggerMode', 'XPixelsDetector', 'NbImagesMax', 'PhotonEnergy', 'Wavelength', 'CountTimeInte', 'CountTime', 'AutoSummationEnabled', 'EnergyThreshold', 'NbImagesMin', 'YPixelsDetector', 'EnergyThresholdMax', 'NbImages', 'CountTimeMax', 'BitDepth', 'Description', 'EnergyThresholdMin', 'FilesInBuffer', 'BeamCenterY', 'BeamCenterX', 'CountTimeMin', 'DcuBufferFree', 'NbTriggers', 'Humidity', 'ReadoutTime', 'FrameTimeMax', 'Error', 'PhotonEnergyMin', 'DetectorDistance', 'FrameTimeMin', 'FlatfieldEnabled', 'XPixelSize', 'RoiMode', 'MustArmFlag', 'RateCorrectionEnabled', 'PhotonEnergyMax', 'OmegaStart', 'State', 'Status'

- Commands:

'Abort', 'Arm', 'Cancel', 'ClearBuffer', 'DeleteFileFromBuffer', 'Disarm', 'DownloadFilesFromBuffer', 'Init', 'State', 'Status', 'Trigger'



Eiger tango device

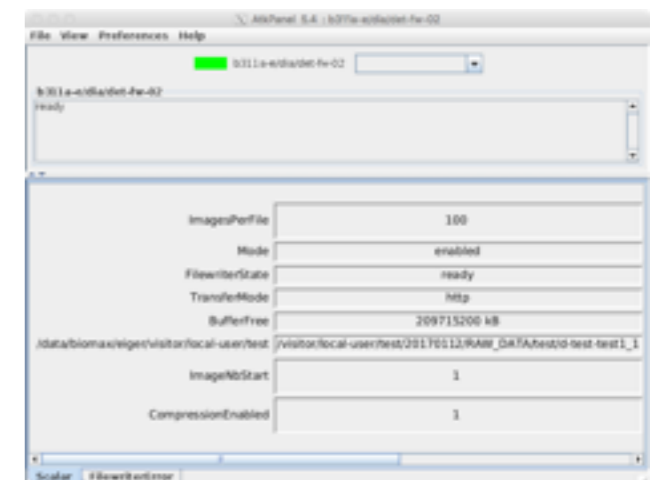
EigerFilewriter class

- Attributes:

'FilewriterError', 'ImagesPerFile', 'Mode', 'FilewriterState', 'TransferMode', 'BufferFree', 'FilenamePattern', 'ImageNbStart', 'CompressionEnabled', 'State', 'Status'

- Commands:

'Clear', 'Init', 'InitializeFilewriter', 'State', 'Status'



Some remarks (v1.6)

- A few undocumented keys in the API
- Parameters that might affect additional parameters
 - answer includes related parameter that have changed
- Long timeouts when arming (< 10 s)
- "Wait" command:
 - No status change when exts/exte, always in ready (in ints you switch between ready/acquire)
 - To see the status updates, send the wait command after the arm
 - Command does not appear in the api doc!
- After arm config parameters do not have effect, arm will apply whatever has been fixed
- Before requesting detector state: send "status_update"
 - this is an internal workaround to be fixed in the next releases
- Detector status and detector head state not synchronized properly

Eiger hwobj

- In HardwareObjects.MAXIV.BiomaxEiger.py
 - *prepare_acquisition*:
OmegaStart, OmegaIncrement, BeamCenterX, BeamCenterY, start, osc_range, exptime, ntrigger, number_of_images, images_per_file, compression, ROI, wavelength, FilenamePattern
 - *start_acquisition*:
 - arm detector and wait for the trigger
- In HardwareObjects.MAXIV.BiomaxCollect.py (from AbstracCollect)
- See Jie's recent PR to mxcube HardwareObjects

```
class BIOMAXEiger(Equipment):  
    """  
    Description: Eiger hwobj based on  
    tango  
    """
```

```
detector.xml  
<equipment class="MAXIV.BIOMAXEiger">  
  <type>EIGER</type>  
  <model>16M</model>  
  <manufacturer>DECTRIS</manufacturer>  
  <file_suffix>h5</file_suffix>  
  <default_exposure_time>0.05</default_exposure_time>  
  <default_compression>bslz4</default_compression>  
  <buffer_limit>50000</buffer_limit>  
  <detector_device>b311a-e/dia/det-02</detector_device>  
  <filewriter_device>b311a-e/dia/det-fw-02</filewriter_device>  
  <width>4150</width>  
  <height>4371</height>  
  <min_trigger_energy_change>10</min_trigger_energy_change>  
  <beam>  
    <ax>-0.00251407429778</ax>  
    <ay>0.00426788308523</ay>  
    <bx>2099.66249149</bx>  
    <by>2139.18150251</by>  
  </beam>  
</equipment>
```

Thanks for your attention!

